# AC0 unpredictability 

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#### Abstract

We prove that for every distribution $D$ on $n$ bits with Shannon entropy $\geq n-a$ at most $O\left(2^{d} a \log ^{d+1} g\right) / \gamma^{5}$ of the bits $D_{i}$ can be predicted with advantage $\gamma$ by an $\mathrm{AC}^{0}$ circuit of size $g$ and depth $d$ that is a function of all the bits of $D$ except $D_{i}$. This answers a question by Meir and Wigderson (2017) who proved a corresponding result for decision trees.

We also show that there are distributions $D$ with entropy $\geq n-O(1)$ such that any subset of $O(n / \log n)$ bits of $D$ on can be distinguished from uniform by a circuit of depth 2 and size $\operatorname{poly}(n)$. This separates the notions of predictability and distinguishability in this context.


A line of papers in the literature [EIRS01, Raz98, Unr07, SV10, DGK17, CDGS18, MW17, ST17, GSV18] proves that if a distribution $D$ on $n$ bits has Shannon entropy $H$ close to $n$ then $D$ possesses several properties of the uniform distribution on $n$ bits. For a discussion and comparison of these results we refer the reader to [GSV18]. In this paper we consider two such properties.

Predictability. Meir and Wigderson prove [MW17] that most coordinates cannot be predicted by shallow decision trees. We state their result next with a slightly optimized bound given soon after by Smal and Talebanfard [ST17].

Theorem 1. [MW17, ST17] Let $D=\left(D_{1}, D_{2}, \ldots, D_{n}\right)$ be a distribution on $n$ bits with $H(D) \geq n-a$. Let $t_{1}, t_{2}, \ldots, t_{n}$ be $n$ decision trees of depth $q$, where $t_{i}$ does not query $D_{i}$. Let $B:=\left\{i \in[n]: \mathbb{P}_{D}\left[D_{i}=t_{i}(D)\right] \geq 1 / 2+\gamma\right\}$. Then $|B| \leq 2 a q / \gamma^{2}$.

The bound in [MW17] is $|B| \leq O\left(a q / \gamma^{3}\right)$. Throughout this paper $O($.$) and \Omega($.$) stand for$ absolute constants. The result in [MW17, ST17] applies to a stronger model that we think of as roughly the intersection of DNF and CNF. But it does not apply to DNF. Meir and Wigderson raised the question of proving a similar result for $\mathrm{AC}^{0}$. We answer their question affirmatively in this paper.

[^0]Theorem 2. Let $D=\left(D_{1}, D_{2}, \ldots, D_{n}\right)$ be a distribution on $n$ bits with $H(D) \geq n-a$. Let $C_{1}, C_{2}, \ldots, C_{n}$ be $n$ circuits on $n$ bits, each of size $g$ and depth $d$, where $C_{i}$ does not depend on $D_{i}$. Let $B:=\left\{i \in[n]: \mathbb{P}_{D}\left[D_{i}=C_{i}(D)\right] \geq 1 / 2+\gamma\right\}$. Then $|B| \leq O\left(2^{d} a \log ^{d+1} g\right) / \gamma^{5}$.

It is noted in [ST17] that Theorem 1 is tight. In a tight example, the decision trees simply compute parities on $q+1$ bits. Such parities can be computed by circuits of depth $\exp \left(q^{1 /(d-1)}\right)$. Hence the bound on $|B|$ in Theorem 2 is tight up to a factor of $\log ^{2}(g) / \gamma^{3}$.

The proof of Theorem 2 is in Section 1.
Distinguishability. A result in [GSV18], stated next, shows that if we forbid to query a few bits, the distribution $D$ is indistinguishable from uniform by small-depth decision trees. (This is called the forbidden-set lemma in [GSV18].)

Theorem 3. [GSV18] Let $D$ be a distribution on $n$ bits with $H(D) \geq n-a$. For every $\gamma, q$ there exists a set $B \subseteq[n]$ of size $O\left(a q^{3} / \gamma^{3}\right)$ such that for every decision tree $t$ of depth $q$ that does not make queries in $B$,

$$
|\mathbb{P}[t(U)=1]-\mathbb{P}[t(D)=1]| \leq \gamma
$$

Theorem 1 can be used to give an alternative proof of Theorem 3, see the discussion in [GSV18]. The other way around is not clear.

In the spirit of the previous result, we ask if Theorem 3 can be extended to constant-depth circuits. We give a negative answer.

Theorem 4. For infinitely many $n$ :
There is a distribution $D$ on $n$ bits with $H(D) \geq n-O(1)$ such that for any set $B$ of size $O(n / \log n)$ there is a read-once $O(\log n)-D N F C$ with no variable in $B$ such that

$$
|\mathbb{P}[C(U)=1]-\mathbb{P}[C(D)=1]| \geq \Omega(1)
$$

The proof of this theorem is in Section 2.
Whereas for the model of decision trees theorems 1 and 3 give similar bounds for predictability and distinguishability, theorems 2 and 4 give a strong separation between these notions for $\mathrm{AC}^{0}$.

Given the negative result in Theorem 4 it is natural to ask if Theorem 3 can be extended in other ways. We note that it is possible to extend it to $q$-DNF, that is DNF with terms of size $q$. However the size of $B$ now depends exponentially on $q$.

Theorem 5. Let $D$ be a distribution on $n$ bits with $H(D) \geq n-a$. For every $\gamma, q$ there exists a set $B \subseteq[n]$ of size $a 2^{O(q)} / \gamma^{O(1)}$ such that for every $q-D N F C$ that does not contain variables in $B$,

$$
|\mathbb{P}[C(U)=1]-\mathbb{P}[C(D)=1]| \leq \gamma
$$

The proof of this theorem is in Section 3.
One can use Theorem 4 to show that the exponential dependence on $q$ in Theorem 5 is necessary. Given $n$ and $q$, use Theorem 4 to obtain a distribution $D^{\prime}$ on $n^{\prime}=2^{\Theta(q)}$ bits with
entropy $\geq n^{\prime}-O(1)$ so that for any set $B$ of size $O\left(n^{\prime} / \log n^{\prime}\right)$ there is a $q$-DNF $C$ with no variable in $B$ such that

$$
\left|\mathbb{P}[C(U)=1]-\mathbb{P}\left[C\left(D^{\prime}\right)=1\right]\right| \geq \Omega(1)
$$

Let $D$ be the distribution that equals $D^{\prime}$ on the first $n^{\prime}$ bits and is uniform on the other $n-n^{\prime}$. The entropy of $D$ is $n^{\prime}-O(1)+n-n^{\prime} \geq n-O(1)$, but for indistinguishability we have to exclude a set $B$ of size $\geq \Omega\left(n^{\prime} / \log n^{\prime}\right)=2^{\Omega(q)}$.

The proofs use standard facts about entropy which can be found online or in the book [CT06]. In particular we use extensively the chain rule $H(X, Y)=H(X)+H(Y \mid X)$ for any random variables $X$ and $Y$. We find it convenient to use the notation $X$ for either the random variable or a fixed sample. The meaning is given by the context. If $X$ is fixed the expression $H(Y \mid X)$ denotes the entropy of $Y$ conditioned on the fixed outcome $X$. If $X$ is not fixed it denotes the average over $X$ of the entropy of $Y$ conditioned on the fixed outcome $X$.

## 1 Proof of Theorem 2

The high-level idea is to perform some kind of restriction so that the circuits collapse to shallow decision trees and also a lot of entropy is preserved. If that happens we can use Theorem 1 to get a bound. However executing this plan is not straightforward.

High-entropy switching lemma. First we recall the switching lemma. It will be important for our results to use the latest analysis [Hås14].

Definition 6. A function $f:\{0,1\}^{m} \rightarrow\{0,1\}^{n}$ is computable by a $q^{\prime}$-partial common decision tree of depth $q$ if there is a (standard) decision tree of depth $q$ such that on every input, the function $f$ restricted along a path of this tree has the property that every output bit of $f$ is computable by a decision tree of depth $q^{\prime}$.

In other words, we can compute $f$ with a decision tree of depth $q$ that has at its leaves decision forests of depth $q^{\prime}$.

A restriction on $n$ bits is a subset of $\{0,1, \star\}^{n}$ where the symbol $\star$ is called star. For an integer $s$ the distribution $R_{s}$ is obtained by picking uniformly a subset of size $s$ for the stars and setting the other bits uniformly.

Lemma 7. [Switching lemma] Let $C:\{0,1\}^{n} \rightarrow\{0,1\}^{n}$ be a circuit of size $g$ and depth $d$ with $g \geq n \geq d$. Let $R=R_{s}$ be a random restriction with $s=\Theta\left(n / \log ^{d-1} g\right)$ stars. Except with error probability $\alpha$ over $R$, the circuit restricted to $R$ can be computed by an $O(\log g)$-partial common decision tree of depth- $O\left(2^{d} \log (g / \alpha)\right)$.

Now we are ready for our switching-lemma for high-entropy distributions.
Definition 8. A $D$-restriction with $s$ stars is obtained by picking the locations for the stars uniformly at random, and setting the other bits according to $D$.

Lemma 9. In the same setting of Theorem 7, let $R$ be a $D$-restriction, where $H(D) \geq n-a$. Then the error bound is $(1+a) / \log (1 / \alpha)$.

For $\sigma$ a subset of $[n]$ we write $D_{\sigma}$ for the $|\sigma|$ bits of $D$ corresponding to $D$, and $D_{\bar{\sigma}}$ for the others.

Proof. Let $A$ be the set of all possible restrictions with $s \star$. We have $|A|=\binom{n}{s} 2^{n-s}$. Let $H$ be the set of restrictions that don't collapse the circuits in the sense of Lemma 7. By the same lemma, $|H| /|A| \leq \alpha$.
$R$ is a distribution over $A$. We shall show that it lands in $H$ with small probability. Write $R$ as $\left(S, D_{\bar{S}}\right)$, where $S$ is the subset of the $\star$, and $D_{\bar{S}}$ is the projection of $D$ outside of $S$. We have

$$
H(R)=H\left(S, D_{\bar{S}}\right)=H(S)+H\left(D_{\bar{S}} \mid S\right) \geq \log _{2}\binom{n}{s}+n-a-s
$$

In the inequality we use that for every fixed $S$, the distribution $D_{\bar{S}}$ is over $n-s$ variables and we have $H(D)=H\left(D_{S}, D_{\bar{S}}\right)=H\left(D_{\bar{S}}\right)+H\left(D_{S} \mid D_{\bar{S}}\right)$. The latter term is at most $s$. And so we have $H\left(D_{\bar{S}}\right) \geq H(D)-s \geq n-a-s$.

Thus the entropy of $R$ is only $a$ away from the maximum entropy $m:=\log _{2}\binom{n}{s}+n-s$ of any distribution over $A$.

Let $p$ be the probability that $R \in H$. Let $E$ be the indicator random variable of the event $R \in H$. We have

$$
\begin{aligned}
m-a \leq H(R) & =H(R, E)=H(R \mid E)+H(E) \leq H(R \mid E)+1 \\
& =p H(R \mid E=1)+(1-p) H(R \mid E=0)+1 \leq p \log _{2}|H|+(1-p) m+1 \\
& \leq p \log \alpha+p m+(1-p) m+1
\end{aligned}
$$

Hence $p \log (1 / \alpha) \leq 1+a$, and the result follows.
We apply Lemma 9 with $\alpha:=2^{-200 a / \gamma}$. This gives an $O(\log g)$-partial common tree of depth $q=O\left(2^{d}(\log g+a / \gamma)\right)$ and an error bound of $0.01 \gamma$.

High-entropy after restrictions. We need to show that after the restriction the entropy is still large. First note $H(D \mid R) \geq s-a$, indeed this holds for any fixed choice for the positions $S$ for the stars. To verify this note that, for any fixed $S$,
$n-a \leq H(D)=H\left(D_{S}, D_{\bar{S}}\right) \leq H\left(D_{\bar{S}}\right)+H\left(D_{S} \mid D_{\bar{S}}\right)=H(R)+H(D \mid R) \leq n-s+H(D \mid R)$.
Applying Markov's inequality to $\mathbb{E}_{R}[s-H(D \mid R)]=s-H(D \mid R) \leq a$, where note the argument inside the expectation is non-negative, we obtain $\mathbb{P}_{R}[s-H(D \mid R) \geq a / \epsilon] \leq \epsilon$ for any $\epsilon$. Setting $\epsilon=0.01 \gamma$ we obtain that with probability $\geq 1-0.01 \gamma$ over $R, H(D \mid R) \geq$ $s-O(a / \gamma)$.

Intersecting $B$. We argue that $|S \bigcap B| \geq 0.5(s|B| / n)=\Omega\left(|B| / \log ^{d-1} g\right)$ with high probability. This quantity is the hypergeometric distribution of the number of red balls sampled without replacement from a set of $n$ balls $|B|$ of which are red. The expected number of red balls is $s p$ where $p:=|B| / n$. The probability of sampling less than half of that is at most (see Section 4 in [Hoe63])

$$
2^{-\mathcal{D}(0.5 p \mid p) s} \leq 2^{-\Omega(p s)} \leq 2^{\Omega\left(|B| / \log ^{d-1} g\right)}
$$

where $\mathcal{D}$ is divergence. The upper bound is at most $1 / 1000$ (else the theorem is vacuously true).

Fixing restrictions. Call a fixed restriction $R$ good if both $H(D \mid R) \geq s-O(a / \gamma)$ and every circuit collapses to an $O(\log g)$-partial common depth- $q$ tree. By above and a union bound, the probability that $R$ is not good is $\leq 0.01 \gamma+0.01 \gamma \leq \gamma / 10$. Writing $R$ as $\left(S, D_{\bar{S}}\right)$ we conclude that

$$
\mathbb{P}_{S}\left[\mathbb{P}_{D_{\bar{S}}}[R \mathrm{bad}] \geq \gamma / 2\right] \leq 1 / 5
$$

because otherwise the probability of being bad is $>(1 / 5)(\gamma / 2)=\gamma / 10$, contradicting the previous fact.

Combining this with the bound on intersecting $B$ we obtain that there exists a fixed $S$ such that
(1) $\mathbb{P}_{D_{\bar{S}}}[R \mathrm{bad}] \leq \gamma / 2$,
(2) $|S \bigcap B| \geq \Omega\left(|B| / \log ^{d-1} g\right)$.

Now, for this fixed $S$, let $L:=S \bigcap B$. Because $L \subseteq B$, we have by assumption

$$
1 / 2+\gamma \leq \mathbb{P}_{i \in L}\left[D_{i}=C_{i}(D)\right] \leq \mathbb{P}_{i \in L}\left[D_{i}=C_{i}(D) \mid R \text { good }\right]+\mathbb{P}[R \text { bad }]
$$

So $\mathbb{P}_{i \in L}\left[D_{i}=C_{i}(D) \mid R\right.$ good $] \geq 1 / 2+\gamma-\gamma / 2 \geq 1 / 2+\gamma / 2$. Fix a good restriction $R$ for which this holds. (Note $S$ was fixed already, so we are just fixing $D_{\bar{S}}$.) Project the resulting distribution onto $S$ and call it $X$. We have $H(X) \geq s-O(a / \gamma)$, the circuit is computable by a $O(\log g)$-partial common depth- $q$ tree, and moreover there is a set $L$ of size $\geq \Omega\left(|B| / \log ^{d-1} g\right)$ such that $\mathbb{P}_{i \in L}\left[X_{i}=C_{i}(X)\right] \geq 1 / 2+\gamma / 2$.

Handling the common part. Now we need to handle the common part of the decision tree. We need to fix the variables along a path so that both the entropy and the prediction is preserved. Let $t$ be the common decision tree. We think of sampling $X$ by first sampling the $q$ bits $Y$ along a path, and then sampling the other $s-q$ bits $Z$, in a fixed order. We want to show that $H(Z \mid Y)$ is large. Indeed,

$$
s-O(a / \gamma)=H(X)=H(Y, Z)=H(Z \mid Y)+H(Y) \leq H(Z \mid Y)+q
$$

The second equality can be verified by noting that $X$ is a function of $(Y, Z)$ and $(Y, Z)$ is a function of $X$. Rearranging and using our bound on $q$ we get $s-H(Z \mid Y) \leq q+O(a / \gamma)=$ $O(q)$. By a Markov argument, the probability over $Y$ that $s-H(Z \mid Y) \geq O(q / \gamma)$ is at most $\gamma / 4$. Call such a $Y$ bad. Like before, we have

$$
1 / 2+\gamma / 2 \leq \mathbb{P}_{i \in L}\left[X_{i}=C_{i}(X)\right] \leq \mathbb{P}_{i \in L}\left[X_{i}=C_{i}(X) \mid Y \text { good }\right]+\mathbb{P}[Y \text { bad }]
$$

Hence $\mathbb{P}_{i \in L}\left[X_{i}=C_{i}(X) \mid Y\right.$ good $] \geq 1 / 2+\gamma / 4$. Fix a good $Y$ such that this holds, and call the resulting distribution $V$. We have $H(V) \geq s-O(q / \gamma)$,

$$
\begin{equation*}
\mathbb{P}_{i \in L}\left[V_{i}=C_{i}(V)\right] \geq 1 / 2+\gamma / 4 \tag{1}
\end{equation*}
$$

and now each $C_{i}$ is a decision tree of depth $O(\log g)$.
Finishing up. By Theorem 1 the number of the $s$ coordinates of $V$ that can be $(1 / 2+\gamma / 8)$ predicted is at most twice the entropy deficiency $O(q / \gamma)$ times the depth of the tree $O(\log g)$, divided by $O(1 / \gamma)^{2}$. This equals

$$
\begin{equation*}
O\left(q / \gamma^{3}\right) \log g \tag{2}
\end{equation*}
$$

Hence we have

$$
\mathbb{P}_{i \in L}\left[V_{i}=C_{i}(V)\right] \leq O\left(q / \gamma^{3}\right) \log (g) /|L|+1 / 2+\gamma / 8
$$

Combining equations 1 and 2 we obtain

$$
O\left(q / \gamma^{3}\right) \log g /|L| \geq \gamma / 8
$$

Now recall $q=O\left(2^{d}(\log g+a / \gamma)\right)$. Hence we can crudely bound $O\left(q / \gamma^{3}\right) \log g$ above by $O\left(2^{d} \log ^{2}(g) a / \gamma^{4}\right)$. Also recall $|L| \geq \Omega\left(|B| / \log ^{d-1} g\right)$. Hence we get

$$
O\left(2^{d} \log ^{d+1}(g) a /|B| \gamma^{4}\right) \geq \gamma / 8
$$

This concludes the proof.

### 1.1 Proof of Lemma 7

We denote by $R_{p}$ the standard distribution on restrictions where the bits are independent and each comes up $1,0, \star$ with probabilities $(1-p) / 2,(1-p) / 2, p$.

Lemma 10. [Lemma 3.8 in [Hås14] with $s:=1+\log S]$ Let $f:\{0,1\}^{n} \rightarrow\{0,1\}^{S}$ be a function computable by a depth-2 circuit with input fan-in $r$. Then the probability over $R_{p}$ that $f$ restricted to $R_{p}$ cannot be computed by a $(1+\log S)$-partial common depth- $q$ decision tree is at most $S(24 p r)^{q}$.

The straightforward corollary we need is not stated anywhere.
Corollary 11. Let $C:\{0,1\}^{n} \rightarrow\{0,1\}^{n}$ be a circuit of size $g$ and depth $d$ with $g \geq n \geq d$. Let $p=\Theta\left(1 / \log ^{d-1} g\right)$. With probability $1-\alpha$ over $R_{p}$ the circuit restricted to $R_{p}$ can be computed by a $(1+\log n)$-partial common depth- $O\left(2^{d} \log (g / \alpha)\right)$ decision tree.

Proof. First we take a restriction with $p=\Omega(1)$, and apply Lemma 10 to the $g_{1}$ gates at level 1 (viewed as a DNF or CNF with input fan-in 1). For a parameter $q_{0}$, with probability $1-g_{1} 2^{-q_{0}}$ we can compute $f$ by a common decision tree of depth $q_{0}$ at the leaves of which we have circuits of depth $d$ whose number of gates at levels $\geq 2$ hasn't changed, and whose input fan-in is $O(\log g)$.

Then we take a restriction with $p=\Omega(1 / \log g)$, and apply Lemma 10 to the $g_{2}$ gates at level 2 . We take a union bound over all $2^{q_{0}}$ paths of the common decision tree just discussed. For a parameter $q_{1}$, with probability $1-2^{q_{0}} g_{2} 2^{-q_{1}}$ we can compute $f$ by a decision tree of depth $q_{0}+q_{1}$ at the leaves of which we have circuits of depth $d-2$ whose inputs are decision trees of depth $O(\log g)$. We can write the latter trees as CNF or DNF as appropriate and merge them with the next layer of gates. Hence we can compute $f$ by a decision tree of depth $q_{0}+q_{1}$ at the leaves of which we have circuits of depth $d-1$ with input fan-in $O(\log g)$. The number of gates at the higher levels hasn't changed.

We continue in this fashion. In the end, we can compute $f$ by a tree of depth $q_{0}+$ $q_{1}+\cdots+q_{d-1}$ whose leaves are forests of depth $O(\log g)$. The error probability is $g_{1} 2^{-q_{0}}+$ $2^{q_{0}} g_{2} 2^{-q_{1}}+2^{q_{0}+q_{1}} g_{3} 2^{-q_{2}}+\cdots$. Picking $q_{i}=t \cdot 2^{i}$ this is at most $g \cdot d \cdot 2^{-t}$.

So for error $\alpha$ we should take $t=\log (1 / \alpha)+\log (g)+\log (d) \leq O(\log g / \alpha)$. This gives a common tree of depth $O(\log g / \alpha) 2^{d}$ whose leaves are forests of depth $O(\log g)$.

To conclude the proof of Lemma 7 we only need to verify that the same result holds if we take a restriction with exactly $s=n p \star$. Indeed, the probability that $R_{p}$ has exactly $s$ stars is $\geq \Omega(1 / \sqrt{s}) \geq \Omega(1 / g)$. So if we set the error probability to $O(\alpha / g)$ in Corollary 11 we obtain an error probability of $\alpha$ for restrictions with exactly $s$ stars, and the depth of the tree hasn't changed asymptotically.

## 2 Proof of Theorem 4

Let $n=m\left(\log _{2} m+1\right)$ and think of the $n$ bits as divided in $m$ blocks of $\left(\log _{2} m+1\right)$ bits each. The distribution $D$ is sampled as follows. First select $I \in\{1,2, \ldots, m\}$ uniformly. Set the $I$ block to all zero. Then for every other block independently, set the block to a uniform value excluding all zero. We can write $D$ as $(I, X)$ where $X$ are non-zero values for $m-1$ blocks.

We have

$$
\begin{aligned}
H(D) & =H(I, X)=H(I)+H(X)=\log _{2} m+(m-1) \log _{2}(2 m-1) \\
& =\log _{2} m+(m-1) \log _{2}(2 m)+(m-1) \log _{2}(1-1 / 2 m) \\
& \geq m \log _{2}(2 m)-O(1)
\end{aligned}
$$

The set $B$ intersects $\leq|B|$ of the blocks. Let $G$ be the other blocks. Consider the function $C$ that outputs 1 if any of the blocks in $G$ is all zero. This function can be written as a read-once DNF with terms of size $\log _{2} m+1$.

Under the uniform distribution, the probability that $C$ equals 1 is at most $m / 2^{\log _{2} m+1}=$ $1 / 2$.

Under $D$ it is at least the probability that $I \in G$, which is $\geq(m-|B|) / m$. So if $|B| \leq m / 3$ the DNF $C$ distinguishes. The result follows because $m \geq \Omega(n / \log n)$.

## 3 Proof of Theorem 5

We rely on a simulation of DNF by decision trees, showing that a $q$-DNF can be written as a tree of depth about $2^{q}$, which may output "?" with small probability. A weaker version of
the result was proved by Ajtai and Wigderson [AW89]. The stronger version, stated next, is due to Trevisan [Tre04].

Lemma 12. For every $q$-DNF $C$ there exists a decision tree $t_{C}$ of depth $\leq 2 q 2^{q} \log (1 / \epsilon)$ with range $\{0,1, ?\}$ such that
(1) for every input $x, t_{C}(x) \neq$ ? $\Rightarrow t_{C}(x)=C(x)$, and
(2) $\mathbb{P}\left[t_{C}(U)=\right.$ ? $] \leq \epsilon$.

Proof. A covering of the terms is a set of variables such that any term contains a variable from the set, possibly negated. We define $t_{C}:\{0,1\}^{n} \rightarrow\{0,1, ?\}$ recursively as follows. If $C$ is a constant then $t_{C}$ is the same constant. If $C$ has $\geq 2^{q} \log (1 / \epsilon)$ disjoint terms, then $t_{C}$ queries the first $2^{q} \log (1 / \epsilon)$ of them. If any term is True, $t_{C}$ outputs 1 , else it outputs ?. Otherwise, there exists a covering of the terms of size $\leq q 2^{q} \log (1 / \epsilon)$. The tree $t_{C}$ first queries this covering, and then recursively queries the resulting ( $q-1$ )-DNF.

The tree $t_{C}$ has depth $\leq q 2^{q} \log (1 / \epsilon)+(q-1) 2^{q-1} \log (1 / \epsilon)+\ldots \leq 2 q 2^{q} \log (1 / \epsilon)$.
Item (1) follows by definition.
To verify Item (2), note that the only case in which $t_{C}$ outputs ? is that none of $\geq$ $2^{q} \log (1 / \epsilon)$ disjoint terms is True. This happens with probability at most

$$
\left(1-1 / 2^{q}\right)^{2^{q} \log (1 / \epsilon)} \leq(1 / e)^{\log (1 / \epsilon)} \leq \epsilon
$$

As a corollary, any distribution which fools decision trees of depth about $2^{q}$ also fools $q$-DNF. We say that a distribution $D \epsilon$-fools a class of functions $F$ if for every $f \in F$ we have $|\mathbb{P}[f(D)=1]-\mathbb{P}[f(U)=1]| \leq \epsilon$, where $U$ is the uniform distribution.

Corollary 13. Let $D$ be a distribution that $\epsilon$-fools decision trees of depth $2 q 2^{q} \log (1 / \epsilon)$. Then $D O(\epsilon)$-fools $q-D N F$.

Proof. For a $q$-DNF $C$ let $t_{C}$ be the tree from Lemma 12. By its properties we have, for every distribution $X$ :

$$
\mathbb{P}\left[t_{C}(X)=1\right] \leq \mathbb{P}[C(X)=1] \leq \mathbb{P}\left[t_{C}(X)=1\right]+\mathbb{P}\left[t_{C}(X)=?\right]
$$

Writing down this fact for both $X=D$ and $X=U$ we have

$$
\begin{aligned}
& \mathbb{P}\left[t_{C}(U)=1\right] \leq \mathbb{P}[C(U)=1] \leq \mathbb{P}\left[t_{C}(U)=1\right]+\mathbb{P}\left[t_{C}(U)=?\right] \\
& \mathbb{P}\left[t_{C}(D)=1\right] \leq \mathbb{P}[C(D)=1] \leq \mathbb{P}\left[t_{C}(D)=1\right]+\mathbb{P}\left[t_{C}(D)=?\right]
\end{aligned}
$$

By assumption, the left-hand sides are within $\epsilon$, and so are the rightmost terms. Moreover, $\mathbb{P}\left[t_{C}(U)=?\right] \leq \epsilon$. Hence $\mathbb{P}[C(X)=1]$ for both $X=D$ and $X=U$ lies in the interval $\left[\mathbb{P}\left[t_{C}(U)=1\right]-\epsilon, \mathbb{P}\left[t_{C}(U)=1\right]+3 \epsilon\right]$ and so they are within $O(\epsilon)$.

Combining Corollary 13 with Theorem 3 we immediately obtain Theorem 5.
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